

Precision in articulation  
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# Effects of predictability and practice on the movement precision during the execution of articulatory gestures

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## Abstract

Typically, when people repeat the movements involved in playing instruments or sports – i.e. *practice* – their kinematic behavior improves: associated movements become more precise. Similar findings have been reported for articulation, with adults’ articulatory gestures being more precisely executed than those of children. Given that practicing speech across the lifespan appears to improve production, it would seem to follow that the frequency with which articulatory movements are usually made ought to have a similar effect. To address this question, the present study investigated articulatory precision during the transition between the German word [zi:] ‘they’ and the following verb, while controlling for the vowel contained in the verb. The articulatory “practice” of [zi:] with each verb was operationalized as the conditional probability of the verb given [zi:], i.e. the degree to which experience of

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a verb is conditioned on [zi:] in context. Considering findings in relation to practice, we find that when the verb contained an [a], i.e. required a *different* vocalic gesture, higher conditional probabilities were associated with greater precision of articulation. By contrast, when the verb contained an [i], such that its production involved the *same* vocalic gesture, no correlation between conditional probability and precision was found. These results indicate that speakers tend to gravitate towards an optimal articulatory trajectory, and that depending on the amount of practice a speaker has with a given gesture, they will tend to follow its path with more or less precision.

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## 1. Introduction

It is well known that kinematic movements show a speed-accuracy trade-off (Fitts, 1954; Wright and Meyer, 1983; Bertuccio and Cesari, 2010): the same movement gesture, when executed faster or longer, will tend to be executed less precisely, i.e. with larger variability; slower or shorter movements will tend to be executed more precisely. Practice, i.e. the repetition of one and the same movement such as throwing a ball, will counteract this trade-off, with either increasing the speed while movement precision remains constant or increasing precision while speed stays constant (Georgopoulos et al., 1981; Darling et al., 1988; Platz et al., 1998; Sosnik et al., 2004; Madison et al., 2013; Raeder et al., 2015).

While speech production is itself the result of a set of kinematic movements, it is also clear that articulation and throwing a ball differ a great deal. Hand movements are effected with a relatively rigid body joint-angle system and usually have one target (cf. as throwing or catching a flying ball, fetching a cup or even hand writing (Bourgeois and Hay, 2003)). By contrast, the articulatory apparatus consists of a rigid bone structure (the jaw) and muscular hydrostats (the tongue). Whereas these are considered to be independent articulators, they are biomechanically joined and task-dynamically coupled (Bell-Berti and Harris, 1979; Saltzman and Munhall, 1989; Fowler and Saltzman, 1993) and produce successive gestures with their own, partially competing, targets which result in a strong overlap between adjacent gestures (Öhman, 1966; Browman and Goldstein, 1986; Magen, 1997).

This underlying kinematic complexity of speech production in contrast to hand movements raises the question how and to what extent practice increases precision during articulation. Studies of the timing of articulation indicate that this may be the case since practice has similar effects onto the timing of articulation like it has onto hand movements (Tiede et al., 2011; Tomaschek et al., under revision 1). In addition, several studies investigating articulation in children and adults show effects are consistent with the effects of practice.

Goffman et al. (2008) investigated anticipatory lip rounding of upcoming rounded vowels in children and adults. Lip rounding has been shown to be time-locked to the vowel's acoustic onset, independently of the number of consonants in the preceding cluster (Bell-Berti and Harris, 1979). Goffman et al. (2008) showed that children's anticipatory lip rounding was executed with smaller temporal precision than that of adults. Similar findings have been obtained from studies of the way that vowel production is affected by anticipatory coarticulation Zharkova et al. (2011, 2012); Belmont (2011). Further convergent findings come from

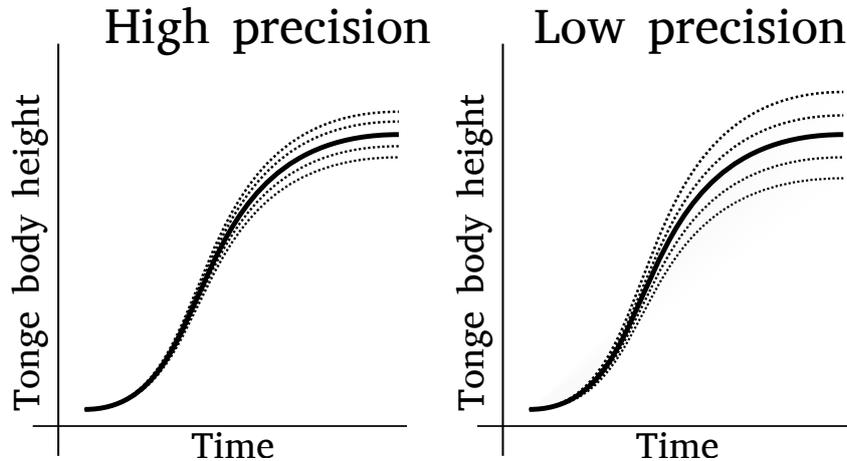


Figure 1: Illustration of high/low precision during articulation of the vowel [i:] in the entire word [zi:] . Dark line represents a hypothetical optimal articulatory trajectory, dashed lines represent actual articulations. Low positions represent the position of the tongue body during the articulation of [z] , high positions represent the tongue body during the articulation of [i:] . Left: High precision, i.e. low variability around an optimal articulatory trajectory. Right: Low precision, i.e. high variability around an optimal articulatory trajectory.

33 Heisler et al. (2010), who investigated how articulatory precision relates to lexical represen-  
 34 tations by examining the articulations of novel words, and found that articulatory patterns  
 35 were more precise when a stronger lexical representation for a word had been established by  
 36 means of a visual referent.

37 These findings support our hypothesis that practice with a word increases the precision with  
 38 which an identical gesture will be executed during speech production.

39 All these findings all indicate that practice – whether as a result of repetition or as a  
 40 result of age – serves to increase articulatory skills. However, none of these couple practice  
 41 and articulatory precision in something as massively overlearned as adult speech, whose  
 42 psychometric performance has been shown to be significantly predictable by frequencies of  
 43 occurrence and conditional probabilities (Whalen, 1991; Aylett and Turk, 2004; Gahl, 2008;  
 44 Bell et al., 2009; Tremblay and Tucker, 2011; Tomaschek et al., 2013, 2014; Ramskar et al.,  
 45 2014; Priva, 2015; Tomaschek et al., under revision 2).

## 46 2. Articulation experiment

47 To examine the effects of practice operationalized by frequencies of occurrence and condi-  
 48 tional probabilities, we investigated the precision of gestural execution during speech produc-  
 49 tion recorded by means of electromagnetic articulography. In a similar fashion to kinematic  
 50 studies, in which usually one movement pattern is investigated (e.g. Viviani and Terzuolo,  
 51 1982; Bourgeois and Hay, 2003), we controlled the shape of tongue movement trajectories  
 52 by focusing on the articulation of a single German word – *sie* [zi:] 'engl. they'. In this way  
 53 we were able to examine multiple instances of an identical articulatory gesture executed  
 54 in differently practiced contexts. Given the foregoing, we expected increased articulatory  
 55 precision, gauged by the size of the error around a hypothetically optimal trajectory, in

56 more frequent ‘[zi:] + verb’ phrases, when the verb is more frequent, and also when [zi:] is  
57 more probable given the verb (see Figure 1, left vs. right). Importantly, the latter measure  
58 was favored because inverse conditional probability is an explicit measure of expectancy, i.e.  
59 practice of [zi:] given the following verb, whereas independently calculated measures such as  
60 the verb’s frequency or the phrase’s bigram frequency alone are not (Shannon, 1948; Baayen  
61 et al., 2013), and because empirically, conditional probability have been shown to account  
62 for behavior better than less informative measures (Arnon and Snider, 2010; Tremblay and  
63 Baayen, 2010).

64 Our method allowed for data on two additional linguistic measures to be collected: antici-  
65 patory coarticulation and speaking rate. The first measure is a consequence of the fact that  
66 [zi:] was produced in an unstressed position of a large number of ‘sie + verb’ phrases, where  
67 the verb contained either a high [i:] or a low [a] . Since unstressed syllables are subjected to  
68 anticipatory coarticulation in the upcoming syllable (Öhman, 1966; Recasens, 1984; Sziga,  
69 1992; Hoole et al., 1993; Magen, 1997; Fowler and Brancazio, 2000; Tomaschek et al., 2013,  
70 2014) we expected the tongue to change movement patterns depending on whether a high  
71 vowel or a low vowel followed. Models of speech production (Bell-Berti and Harris, 1979;  
72 Browman and Goldstein, 1986; Saltzman and Munhall, 1989; Fowler and Saltzman, 1993)  
73 predict that the tongue will have only one vocalic target in the former case, but two in the  
74 latter. As two vocalic targets increase the complexity of the sequence – because two gestures  
75 need to be coordinated – articulatory variability ought to be larger in [zi:] + [a] verb phrases  
76 than in [zi:] + [i:] verb phrases.

77 The second linguistic measure afforded by our procedure was the manipulation of speaking  
78 rate: (*fast* vs. *slow*). Given Fitt’s Law (Fitts, 1954), we expected to find larger variability in  
79 the fast speaking rate condition than in the slow speaking condition, and additionally, given  
80 the natural temporal variations we could expect to encounter during speech production, we  
81 expected to find higher variability in the production of longer words and longer vowels.

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## 82 2.1. Stimuli

83 The focal word examined in our investigation was the German pronoun *sie* [zi:] ‘they’. (A  
84 series of complementary investigations of the production of the same words were reported in  
85 Tomaschek et al. (2014) – and reanalyzed in Tomaschek et al. (under revision 2) – studied  
86 the effect of frequency of use on the articulation of vowels in German verbs presented in the  
87 context of *sie* ‘they’ or *ihr* ‘you, pl.’). In the present study, every participant articulated  
88 the word *sie* roughly 378 times during the experiment. Verbs were controlled for relative  
89 frequency of use, i.e. token count divided by corpus size, taken from the SDEWAC corpus  
90 (~900 million entries, Shaoul and Tomaschek, 2013; Faaß and Eckart, 2013). Verbs contained  
91 the vowels [i, i:, a:, a], respectively, in the first stressed syllable. For the present analysis,  
92 only verbs with a single non-dorsal onset consonant were considered (in total 63 [i] and 64  
93 [a] verbs). 55 verbs began with a coronal consonant, 55 with a labial.

94 *2.2. Speakers and Recording*

95 A total of 21 German native speakers were recorded and paid 15€ for their participation.  
96 All speakers signed an informed consent form agreeing to their participation. Speaker  
97 identity was anonymized by means of experiment related identifiers. 4 speakers had to  
98 be excluded from the analysis due to missing data or faulty sensors. Of the remaining  
99 speakers in the analysis, 9 were females and 8 were males, with their mean age being 25.6  
100 (sd= 3). All recordings were conducted in a sound-attenuated booth at the Department  
101 of Linguistics of the University of Tübingen. Speakers were instructed to read the stimuli  
102 ([zi:] + verb) aloud after they appeared on a computer screen. Each word in each context  
103 was presented once. The list was pseudo-randomized for each participant and divided into  
104 three parts. Each part was presented once in a *slow* (odd blocks, inter-stimulus-time: 600  
105 ms; presentation-time: 800 ms) and once in a *fast* speaking condition (even blocks, inter-  
106 stimulus-time: 300 ms; presentation-time: 450 ms). In total, 6 blocks of stimuli were  
107 presented. Participants' tongue movements during articulation were recorded with an NDI  
108 wave articulograph at a sampling frequency of 100 Hz. Simultaneously, an audio signal of the  
109 sounds produced by these articulation was recorded (Sampling rate: 22.05 kHz, 16bit) and  
110 synchronized with the recordings from the articulograph. To correct for head movements  
111 and to define a local coordinate system, a special 6D reference sensor was attached to the  
112 speakers' forehead. Before sensors were attached to a participant's tongue, a recording was  
113 made to determine the rotation from the local reference to a standardized coordinate system.  
114 The standardized coordinate system was defined by a bite plate to which three sensors in a  
115 triangular configuration were attached. Tongue movements were captured by three sensors:  
116 one slightly behind the tongue tip, one at the tongue middle and one at the tongue dorsum  
117 (distance between each sensor: approximately 2cm). The analyses presented below focus  
118 on the sensor located near the tongue dorsum (the sensor located farthest back), which  
119 is considered least affected by non-dorsal consonants during the articulation of the vowel  
120 (Fowler, 1980; Öhman, 1966).

121 *2.3. Preprocessing*

122 Tongue movements were corrected for head-movements in an online procedure during record-  
123 ing. The recorded positions of the tongue sensors were centered at the midpoint of the bite  
124 plate and rotated in such a way that the back-front direction of the tongue was aligned  
125 to the horizontal axis with more positive values towards the front of the mouth, and more  
126 positive vertical values towards the top of the oral cavity. Word boundaries were deter-  
127 mined by automatically aligning the audio signal with phonetic transcriptions by means of  
128 a Hidden-Markov-Model-based forced aligner for German (Rapp, 1995). Alignments were  
129 manually verified and corrected where necessary. Complete documentation and data are  
130 available at the Open Science Framework (<https://osf.io/r78mk/>), and will be downloadable  
131 upon publication).

Table 1: Summary of generalized additive mixed-effects model investigating effects of Sie Duration and Vowel Proportion on vertical tongue dorsum movement. Effects in the bottom half represent random effects. Legend: SD = Sie Duration , VP = Vowel Proportion , SR = Speaking Rate Condition , NV = Next Vowel , SieProb= Sie Probabilities

Effect	edf	F-value	p-value
te(Time,SD,VP):SRslow	50.81	13.84	<0.0001
te(Time,SD,VP):SRfast	71.49	11.11	<0.0001
te(Time,SD,VP):NVa	34.45	10.44	<0.0001
te(Time,SD,VP):NVi	31.42	6.92	<0.0001
s(Time,Participant)	138.31	63.27	<0.0001
s(SieProb,Participant)	121.72	4.38	<0.0001
s(Time,NextWord)	575.52	1.38	<0.0001
s(Time,Block)	15.40	13.09	<0.0001

### 3. Analysis

#### 3.1. Assessing an optimal articulatory trajectory

In order to examine articulatory variability, we first needed to find an optimal articulatory trajectory for [zi:] against which any variation could be gauged. In obtaining this optimal trajectory, we controlled for known effects of temporal variation (i.e. word duration, vowel duration, Lindblom (1963); Gay (1978); Hertrich and Ackermann (2000)), for known effects of contextual variation due to neighboring consonants (Öhman, 1966; Sziga, 1992; Hoole et al., 1993) and form known effects of speaker variation Winkler et al. (2006); Fuchs et al. (2008); Brunner et al. (2009); Weirich and Fuchs (2006); Rudy and Yunusova (2013) in the random effects structure of our data. The use of Generalized Additive Mixed-effects Models (GAMM, package *mgcv*, Version 1.8-22 Wood (2006)) allowed us to do exactly this. GAMMs model non-linear functional relations between a response and one covariate – wiggly curves – by means of smooths and non-linear functional relations between a response and two or more covariates – (hyper)surfaces – by means of tensors. See Wieling et al. (2016) for a detailed description of GAMMs and their application to articulatory data.

The GAMM model was used to estimate an optimal articulatory trajectory, given the possible contextual, temporal and individual variation. From this the error around that optimal trajectory, i.e. the model’s residuals, was then extracted to serve as a measure of variability around the optimal trajectory, with the residuals also being submitted to further statistical analysis (see Section 3.2.1 and Figure 1 for an illustration of variability around an optimal trajectory). (Although earlier studies of the variability in articulation simply report standard deviations in their analyses (Goffman et al., 2008; Heisler et al., 2010; Cho, 2001), approaches similar to that employed here have been reported in more recent studies: Sonderegger (2015), Sonderegger et al. (2017) and Chodroff and Wilson (2017) investigating the variation of VOTs by means of the residuals of a linear mixed-effects model.)

In exploratory pilot analyses, we first built our models using bottom-up and top-down fitting procedures and used the difference in maximum likelihood scores and edfs to test whether more complex models improved the model fit (van Rij et al., 2015). Improvement was further validated by means of contour plots. The following list presents the set of predictors we used

161 in our GAMM analysis for predicting vertical tongue body position across time. All numeric  
162 variables were  $\log_{10}$  transformed in order to obtain normally distributed data and centered  
163 and scaled in order to reduce possible correlations between random effects.

164 • Normalized time: ***Time*** In order to be able to match the articulatory trajectories in  
165 different [zi:] durations, durations were normalized into range between 0 and 1.

166 • Speaking rate condition: ***SpeakingRateCondition*** As described above, speech rates  
167 were binary categorized as either fast or slow.

168 The vowel in the verb following [zi:]: ***NextVowels*** The vowel category in the following  
169 verb was classified as either [a] or [i:] . This predictor differentiates between those  
170 conditions in which the tongue body maintained its articulatory target (i.e. articulated  
171 a sequence of two [i:] ) and those conditions in which the tongue body changed its  
172 articulatory target (i.e. articulated a sequence of [i:] and [a] ).

173 • Acoustic durations of [zi:]: ***SieDurations*** In spite of the two speaking rate conditions,  
174 visual inspections showed that there was a high overlap in acoustic durations between  
175 the two conditions.

176 • Proportion of [i:] in [zi:] : ***VowelProportions*** Usually, another significant predictor  
177 of tongue position is vowel duration (Gay, 1978; Lindblom, 1963). However, vowel  
178 duration is strongly correlated with word duration and including it as a predictor  
179 would introduce collinearity into the model, increases the risk of Type 1 and Type  
180 2 errors Tomaschek and Hendrix (under revision); Chatterjee and Hadi (2012, c.f.).  
181 We found that vowel proportions, with proportions calculated by dividing the vowel's  
182 duration by the [zi:] duration, did not introduce strong collinearity.

183 • We used Google counts of the verb form (*VerbFrequency*), Google bigram counts of the  
184 "sie + verb" phrase (*BigramFrequency*), and the conditional probability of "sie" given  
185 the following verb (*SieProbabilities*), calculated by dividing Google bigram counts by  
186 Google verb form counts. We will call these *lexical measures* in the remainder of the  
187 text to refer to them collectively.

188 Articulatory data constitute a time series with strong autocorrelation which results in strong  
189 autocorrelated residuals (i.e. one can predict the value at T+1 given the value at T). Resid-  
190 ual autocorrelation results in anti-conservative p-values. We controlled autocorrelation in  
191 the residuals by an AR(1) parameter in our model (Wieling et al., 2015, 2016). We fur-  
192 ther controlled for the following random effects using *random factor smooths* (i.e. random  
193 smooths for factors) that can be regarded as non-linear equivalents of a combination between  
194 random intercepts and random slopes in mixed-effects regression:

195 1. Random factor smooths as a function of *Time* per speaker. This random factor smooth  
196 controls for speaker dependent variations during the production of [zi:] .

- 197 2. It is very well known that tongue positions during the entire vowel articulation are  
198 affected by near and far neighboring consonants (Öhman, 1966; Recasens, 1984; Sziga,  
199 1992; Hoole et al., 1993; Magen, 1997; Fowler and Brancazio, 2000; Tomaschek et al.,  
200 2013, 2014). In order to control for this effect, we included random factor smooths as  
201 a function of *Time* per *verb*. Consequently, this random factor smooth controls for  
202 anticipatory coarticulation, which is not the focus of the current study.
- 203 3. Random factor smooths as a function of *Time* per *presentation block*. This random  
204 factor smooth was included in order to account for fatigue effects during the experi-  
205 ment.
- 206 4. Random factor smooths as a function of *Sie Probabilities* per *speaker*. Although our  
207 probabilistic measures were not significant in pilot analyses (see below for explanation),  
208 we included this random smooths in order to control for possible by participant effects  
209 as a function of *Sie Probabilities* .

210 GAMMs model how the *intercept* (in the parametric summary), i.e. the mean tongue body  
211 position, is changed by the fixed effects. We found that the tongue body position was  
212 significantly predicted by two four-way interactions (Table 1).

- 213 • a) between *Time*, *Sie Duration* , *Vowel Proportion* and *Speaking Rate Condition* ;
- 214 • b) between *Time*, *Sie Duration* , *Vowel Proportion* and *Next Vowel* .

215 Interactions of numeric predictors were modelled by means of a tensor product, including  
216 both, main effects as well as interactions (*te()*, similar to a  $A \times B \times C$  formula in linear  
217 models). The tensor’s interaction with the factorial predictors *Speaking Rate Condition* and  
218 *Next Vowel* is indicated by the colon. Edfs represent estimated degrees of freedom, indicating  
219 how many smoothing functions on average were needed to fit the data. P-values lower than  
220 0.01 indicate significant non-linearity of the model term. No interaction between *Speaking*  
221 *Rate Condition* and *Next Vowel* as well as no effect of *Sie Probabilities* was found. The  
222 final model had  $R^2 = 0.85$ . The highly complex model was supported by means of ML-score  
223 comparison with a less complex model lacking the interactions.

224 Importantly, none of the lexical measures emerged as a significant predictor of articulatory  
225 trajectory in these preliminary models. One major reason is probably that [zi:] was highly  
226 repetitive in our experiment. Even though its conditional probability given the following  
227 word varied, the conditional probability of [zi:] in the experiment itself very soon asymptoted  
228 to roughly 0.5, as [zi:] occurred in roughly 50% of the trials at the beginning of the utter-  
229 ance. The estimated tongue body positions across time and their complex interaction with  
230 *Sie Duration* , *Vowel Proportion* , *Speaking Rate Condition* , *Next Vowel* can be inspected  
231 in the supplementary material. For illustrational purposes, we report here the estimated  
232 vertical tongue body positions across time in interaction with *Vowel Proportion* and *Next*  
233 *Vowel* for [zi:] instances of 220 ms. We chose *Vowel Proportion* , as this predictor turned  
234 out to be predictive for articulatory variability.

235

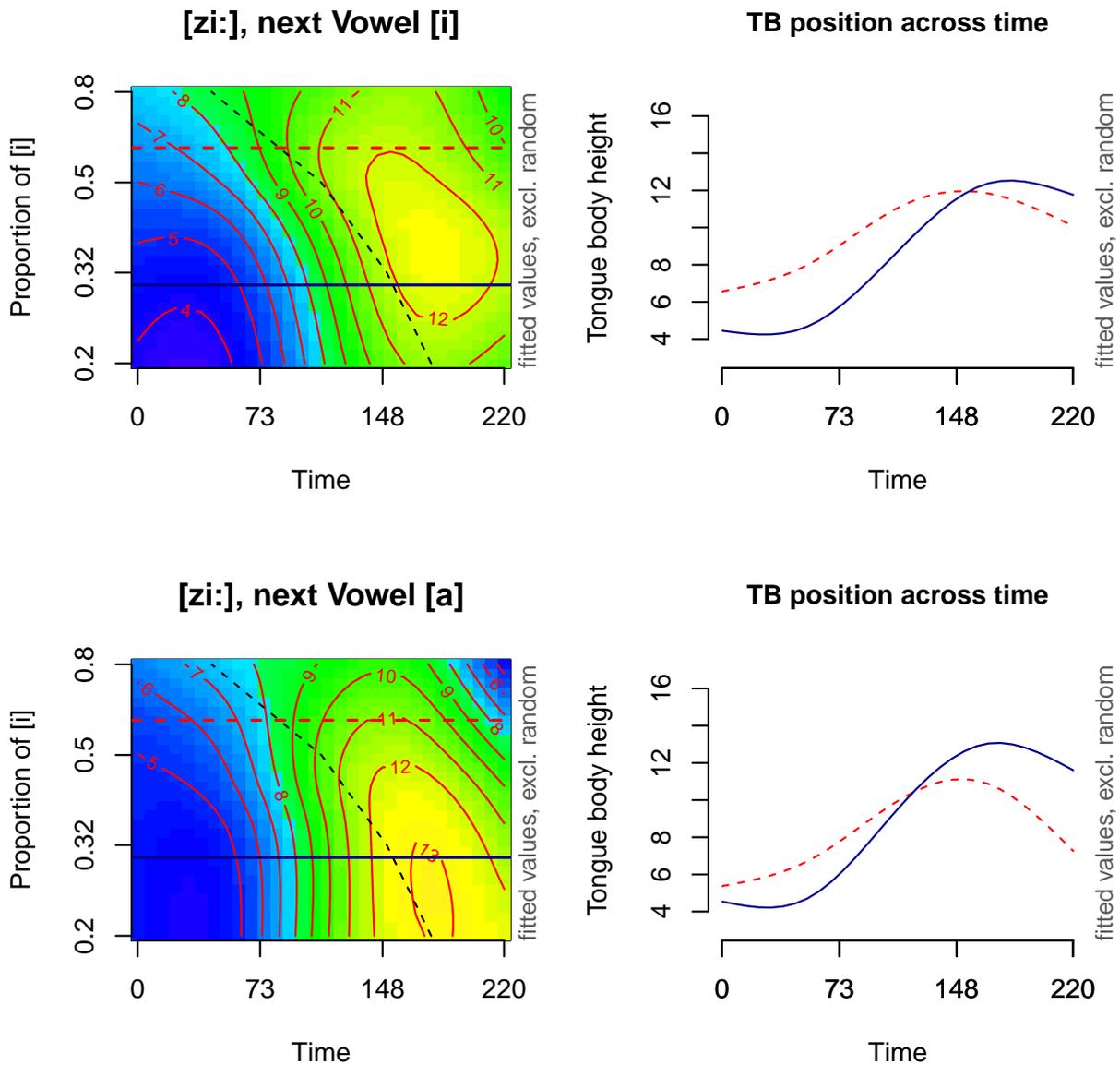


Figure 2: Predictions for vertical tongue dorsum movement as a function of time based on the generalized additive model in Table 1. Random effects were excluded from the predictions. Rows represent different (WD). Columns represent Next Vowel / Speaking Rate Condition conditions. X-axis in plots represents normalized time, Y-axis represents the proportion of [i:] in [zi:]. Contour lines connect areas of the same tongue dorsum height. Values are in mm. Light yellow colors represent areas where the tongue is high, dark blue colors represent areas where the tongue is low (color online). The diagonal dashed line indicates the acoustic boundary between [z] and [i:]. All relevant values were back transformed to raw values for visualization.

236 Before presenting the analysis of variability observed in this study, we describe how articulatory trajectories for [zi:] varied, focusing in particular on the effects of *Sie Duration*, *Vowel*

238 *Proportion and Next Vowel* .

239 The top panel of Figure 2 illustrates the tongue body movements in those instances of  
240 [zi:] that are followed by verbs containing an [i:] . The x-axis of the contour plot (left  
241 column) represents time, the y-axis represents the proportion of the vowel in the entire  
242 [zi:] syllable (i.e. including the articulation of [z]). Areas with low tongue body positions are  
243 encoded in blue, areas with high tongue body positions are encoded in yellow, and inter-  
244 mediate positions are encoded in green; the contour lines represent positional distances of 1  
245 mm. The quasi-diagonal black dashed line represents the acoustic boundary between [z] and  
246 [i:]. With increasing *Vowel Proportion* , it is shifted towards the onset of [zi:] . Exemplarily,  
247 two slices from the *Vowel Proportion* continuum are illustrated in the right column, one for  
248 -1.5 and one for 1.5 standard deviations ( $\sim 0.3$ , blue line /  $\sim 0.6$ , red dashed line) away  
249 from the mean.

250  
251 In the plots, higher tongue body positions at the onset of [zi:] are associated with higher  
252 *Vowel Proportion* (compare the blue and red lines in the right column). This difference  
253 is maintained until the last quarter of [zi:] . Furthermore, in words with high *Vowel Pro-*  
254 *portion* the highest deflection is reached earlier than in words with low *Vowel Proportion* .  
255 It appears that tongue body trajectories are smoother in words with longer acoustic vowel  
256 durations than in words with shorter acoustic vowel durations (i.e. high vs. low *Vowel Pro-*  
257 *portion* ). In the latter, due to the shorter vocalic time window, the tongue body shows  
258 effects of an overshoot, probably due to higher movement velocities during rising (as can be  
259 seen in the steeper rising trajectory in the blue line). Consequently, there are higher tongue  
260 positions at [zi:] offset in words with lower *Vowel Proportion* than in words with higher  
261 *Vowel Proportion* , in spite of a lowering of the tongue body at the offset.

262  
263 The movement pattern observed in instances of [zi:] that are followed by verbs containing an  
264 [a] looks similar (Figure 2, bottom panel), but differs in three respects as a result of anticipa-  
265 tory coarticulation. First, the difference in the first quarter of [zi:] between words with high  
266 *Vowel Proportion* and words with low *Vowel Proportion* is smaller. This is mainly because  
267 the articulatory trajectory in words with high *Vowel Proportion* is lower when [zi:] precedes  
268 words with [a] as compared to verbs with [i:] . Second, as a consequence, tongue height  
269 differs at the maximum deflection point. Surprisingly, it is higher in words with low *Vowel*  
270 *Proportion* when [zi:] precedes verbs with [a] than when it precedes words with [i:] . Third,  
271 anticipating the lower [a] , the tongue body is lowered in strong contrast to when [zi:] pre-  
272 cedes verbs containing [i:] . However, this is only the case in instances of [zi:] with high  
273 *Vowel Proportion* , i.e. when the tongue has enough time during the acoustic production of  
274 the vowel the execute the movement. Overall, we also observe a high degree of systematic,  
275 complex structure during the production of [zi:] , as a result of both temporal variations  
276 in [zi:] and variation across the word boundary. It is these temporal changes that we can  
277 expect to affect articulatory variability at the transition between [zi:] and the following verb.

278

## 279 3.2. Analysis of articulatory variance

### 280 3.2.1. Preprocessing and modeling strategy

281 We used the GAMM model described above as a basis for the next set of analyses. Since  
282 we included random factor smooths as a function of time per speaker and per item as well  
283 as as a function of *Sie Probabilities* per speaker, we can expect to have covered a maximum  
284 of the variance in the data, a suggestion further supported by the model selection criterion.  
285 In line with Cho (2001), who analyzed errors around means, and Sonderegger (2015), Son-  
286 deregger et al. (2017) and Chodroff and Wilson (2017), who analyzed residuals from linear  
287 mixed-effect regression models, we used the residuals from the GAMM model, i.e. the error  
288 between the predicted optimal articulatory trajectory of [zi:] and the recorded articulatory  
289 trajectory in the following analysis of articulatory variance. In particular, because we were  
290 interested in absolute variation, we used the absolute residuals, which were log-transformed  
291 in order to obtain normally distributed data. In these analyses, high values of residuals will  
292 be interpreted as high variability, as they indicate that the articulated trajectory strongly  
293 deviates from an optimal trajectory (see Figure 1 for an illustration of variability around  
294 an optimal trajectory). In the remainder of the text, *smaller residuals* and *lower variability*  
295 will be used as synonyms, depending on the context and focus of the section.

296 Since we lack a precisely defined target for the articulatory movement of the tongue body,  
297 we focus instead on the tongue body's movement during anticipatory coarticulation in the  
298 last 10% of [zi:] , i.e. the transition between [zi:] and the following word. We fitted absolute  
299 logged residuals with linear mixed-effect regression (package *lme4*, Version 1.1-12, Bates et al.  
300 (2014)). We removed potential outliers by removing datapoints larger than 2.5 standard  
301 deviations away from the mean (N = 129, 2.5% of the data). During modeling, we used  
302 *Speaking Rate Condition* , *Sie Duration* , tongue body's vertical *movement velocity*, *Vowel*  
303 *Proportion* , *Next Vowel* and *next length* contrasting between short lax and long tense vowels  
304 as fixed effects. We included *Speakers* and *NextWord* as random intercepts.

305 *VerbFrequency* and *BigramFrequency* show high collinearity ( $r = 0.85$ ), which is why they  
306 could not be included simultaneously into one model (Hadi, 1988; Tomaschek and Hendrix,  
307 under revision). Instead, we created additional versions of the model described above which  
308 included these predictors on an individual basis.

### 309 3.2.2. Results

310 Pilot modeling showed significant interactions between *Next Vowel* and *Vowel Proportion* ( $\beta$   
311 = 0.12,  $se = \beta = 0.03$ ,  $t = \beta = 4.21$ ) as well as between *Next Vowel* and *Sie Probabilities* ( $\beta$   
312 = -0.08,  $se = \beta = 0.04$ ,  $t = \beta = -2.15$ ). In contrast to our hypothesis, no main effect of the  
313 following vowel onto variability was attested ( $\beta = 0.01$ ,  $se = \beta = 0.04$ ,  $t = \beta = 0.24$ ).

314 To reduce the complexity of each model and highlight the effects of lexical measures, we  
315 analyzed each vowel with an individual model, fitting absolute residuals as a function of  
316 *Speaking Rate Condition* , *Vowel Proportion* , *Sie Duration* and *Sie Probabilities* . *Movement*  
317 *velocity* and *next length* failed to yield any significant effect in any of the models and were  
318 excluded from the analysis. It is however possible that *movement velocity* towards a target  
319 plays a more important role rather than away from the target, which occurred roughly before  
320 the offset of the vowel (cf. Figure 2).

Table 2: Summary of partial effects in the linear mixed-effects models investigating effects on articulatory residuals in the transition between [zi:] and the following verb, containing [i:] (upper half) or [a] (lower half). Estimates for predictors marked by \* are taken from a different model. See Section 3.1 for details on predictors.

Partial effect	Next vowel	Estimate	Std.Error	t-value
(Intercept)	[i]	-0.045	0.097	-0.467
SpeakingRateConditionfast	[i]	0.147	0.042	3.489
VowelProportions	[i]	0.034	0.022	1.517
SieDurations	[i]	0.008	0.025	0.303
SieProbability	[i]	-0.005	0.029	-0.156
*VerbFrequency	[i]	-0.045	0.025	-1.811
*BigramFrequency	[i]	-0.043	0.024	-1.811
(Intercept)	[a]	-0.029	0.082	-0.350
SpeakingRateConditionfast	[a]	0.125	0.043	2.937
VowelProportions	[a]	0.161	0.022	7.481
SieDurations	[a]	0.055	0.025	2.176
SieProbability	[a]	-0.091	0.031	-2.970
*VerbFrequency	[a]	-0.001	0.033	-0.027
*BigramFrequency	[a]	-0.001	0.031	-0.027

321 According to Fitt’s law, variability is proportional to movement speed and movement dura-  
322 tion (Fitts, 1954; Wright and Meyer, 1983; Bertuccio and Cesari, 2010). We observe an effect  
323 consistent with this in the present study: Absolute residuals were significantly larger in the  
324 fast speaking rate condition than in the slow speaking rate condition preceding verbs with  
325 both vowels (Table 2, cf. *Speaking Rate Condition* ). No further interactions with speaking  
326 rate condition were found in these analyses.

327 When [zi:] preceded verbs with [i:] , all predictors apart from *Speaking Rate Condition* failed  
328 to yield significance (Table 2, upper half). If [i:] in [zi:] and [i:] in the following verb would  
329 have been represented by two rather than one vocalic target, executed by two gestures, one  
330 would expect that during the articulation of [zi:] temporal variation increases the variability  
331 during the interpolation from one to the second gesture. Since this is not the case, this null  
332 results indicate that [i:] in both words is represented by one gesture. Given that *next length*  
333 was not supported as a significant predictor, it is reasonable to assume that the distance  
334 in tongue height between the short lax and the long tense instance of [i:] was too small to  
335 account for a change in target location.

336 The temporal predictors *Speaking Rate Condition* , *Sie Duration* and *Vowel Proportion* were  
337 correlated positively with the absolute residuals only when [zi:] preceded verbs with [a] ,  
338 (Table 2, lower half). Again, the result is perfectly consistent with Fitt’s law: It appears  
339 that longer macroscopic and microscopic articulation times increase the probability that the  
340 tongue will deviate from an optimal trajectory, resulting in larger variability. Further, this  
341 indicates that articulatory movement variability is not affected by the global tongue body  
342 movement, but rather that it is only influenced by the duration of the relevant movement  
343 necessary to produce the acoustic signal. In other words, when the tongue body has more  
344 time to execute a movement, movements that are on the whole rather similar tend to vary  
345 more markedly.

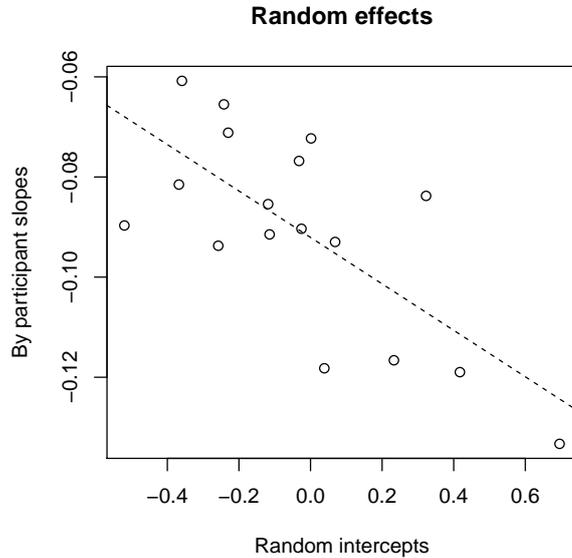


Figure 3: *By participant slopes for Sie Probabilities plotted against by participant random intercepts.*

346 One of the hallmarks of increasing kinematic skills due to practice is an increase in precision  
 347 during a movement (Segalowitz and Segalowitz, 1993; Darling et al., 1988; Georgopoulos  
 348 et al., 1981; Platz et al., 1998; Madison et al., 2013). We examined three ways of gaug-  
 349 ing practice: of these, *VerbFrequency* and *BigramFrequency* did not emerge as significant  
 350 predictors for absolute residuals (Table 2, c.f. effects marked by stars).

351 However, and importantly, the inclusion of *Sie Probabilities* results in a better model fit,  
 352 as indicated by a  $\chi^2$ -test ( $\chi^2_{(9,10)} = 7.81$ ,  $p = 0.01$ ). This indicates that the more probable  
 353 [zi:] given the following word, i.e. the easier it is to plan it, the better the tongue follows  
 354 a hypothetical, optimal spatial pathway. This was the case across all speakers, as can be  
 355 seen in Figure 3, which illustrates the by-participant slopes (y-axis) plotted against by-  
 356 participant random intercepts (x-axis). All speakers show negative adjustments of random  
 357 slopes, i.e. reduction of variability across *Sie Probabilities*. Speakers with a greater articu-  
 358 latory variability benefited more from higher *Sie Probabilities* ( $R = -0.71$ ,  $t_{15} = -3.88$ ,  $p =$   
 359  $0.001$ ).

360 This result is in line with findings that frequencies of occurrence are less informative for  
 361 behavior than conditional probabilities (Shannon, 1948; Arnon and Snider, 2010; Tremblay  
 362 and Baayen, 2010; Baayen et al., 2013). This is perhaps surprising. However, unlike the other  
 363 frequency measures, the conditional probability measure captures the variance in amount  
 364 of practice that speakers can be expected to have of [zi:] in the context of a given verb  
 365 (i.e., it represents the amount of practice associated with any given instance of articulatory  
 366 planing). Given the experimental set up, this measure was thus always likely to be more  
 367 informative than the simple counts.

#### 368 4. Summary and conclusion

369 Kinematic studies of hand movements repeatedly indicate that practice, i.e. the repetition of  
370 the same movement, increases precision associated with later performance of that movement  
371 (Darling et al., 1988; Georgopoulos et al., 1981; Platz et al., 1998; Bourgeois and Hay, 2003;  
372 Madison et al., 2013; Raeder et al., 2015), and in speech, a similar pattern of effects has been  
373 observed in articulation as speaker age increases (Goffman et al., 2008; Zharkova et al., 2011,  
374 2012; Belmont, 2011). Here, we sought to see whether practice operationalized in terms of  
375 the probability of one identical gesture given another also reflected the effects of practice on  
376 the precision in an identical gesture executed in different environments (cf. Figure 1).

377 The effect of practice was dependent on the stem vowel in the verbs. When [zi:] preceded  
378 verbs with [i:] , no effects of practice were found; rather, these effects only emerged when  
379 [zi:] preceded [a] . Given that only labial and coronal intervocalic consonants were present  
380 in the data set at hand, a possible explanation for this difference is that the two acoustic  
381 instances of [i:] were represented by one vocalic target, articulated by a single tongue body  
382 gesture (Browman and Goldstein, 1986; Saltzman and Munhall, 1989). This would suggest  
383 that no temporal and articulatory coordination, as well as no interpolation between the two  
384 [i:] vowels was necessary in this case, and that speakers' uncertainty about the articulatory  
385 gesture in the verb's stem vowel was minimal during their productions of [zi:] . If this is  
386 correct, then it follows that no local effects of practice could arise. By contrast, producing the  
387 acoustic sequence [i:] and [a] involves two consecutive gestures, with the resulting trajectory  
388 being an interpolation between the two targets. In this case, it follows that the more  
389 practiced that trajectory is, the more precisely the tongue body will be able to follow a  
390 hypothetically optimal trajectory.

391 Within frameworks in which higher conditional probabilities and frequencies of occurrence  
392 are associated with faster lexical access (Bell et al., 2009; Gahl, 2008), the current findings  
393 could be explained by the additional time speech production gains from the faster access.  
394 With a longer preparatory window articulation can be planned in more detail, resulting in  
395 a less variable trajectory. From the perspective of the task-dynamic model (Saltzman and  
396 Munhall, 1989), which regards the executed articulatory trajectories to be interpolations  
397 between gestures and targets, a less variable trajectory at the word boundary probably  
398 indicates a smoother transition between two consecutive gestures, and possibly a stage,  
399 in which the two gestures are merged into a single one. Similar findings have also been  
400 presented in kinematic studies (Sosnik et al., 2004).

401 Previous studies have shown that frequencies of occurrence and conditional probabilities are  
402 associated with strong changes of spatio-temporal coordination of articulatory movements  
403 and their resulting phonetic signal (Aylett and Turk, 2004; Bell et al., 2009; Tremblay and  
404 Tucker, 2011; Priva, 2015; Tomaschek et al., under revision 1, 2013, 2014, under revision 2).  
405 Taken together with the current results, these findings indicate that practice, as gauged by  
406 lexical measures, serves to change fine articulatory details in speech production suggesting  
407 that the fine grained kinematic skills employed by speakers during articulation constantly  
408 improve with practice. Consequently, like other psychological behavior, speech production is  
409 submitted to an ongoing fine tuning and mirrors the dynamics of life-long learning (Ramscar

410 et al., 2014).

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